

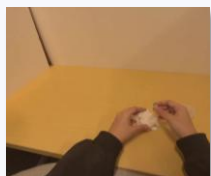
Ego Mid Training

Ego Labeled Data

Object Interaction



Pour Water



Knead Slime

Kitchen Activity



Stir Food



Hand Manipulation

Ego Unlabeled Data

Household Activity



Wash Vegetables



Pour Grain

Fine Manipulation



Factory Assembly

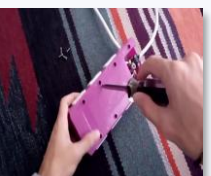


Object Handling

Diverse Hand Skills

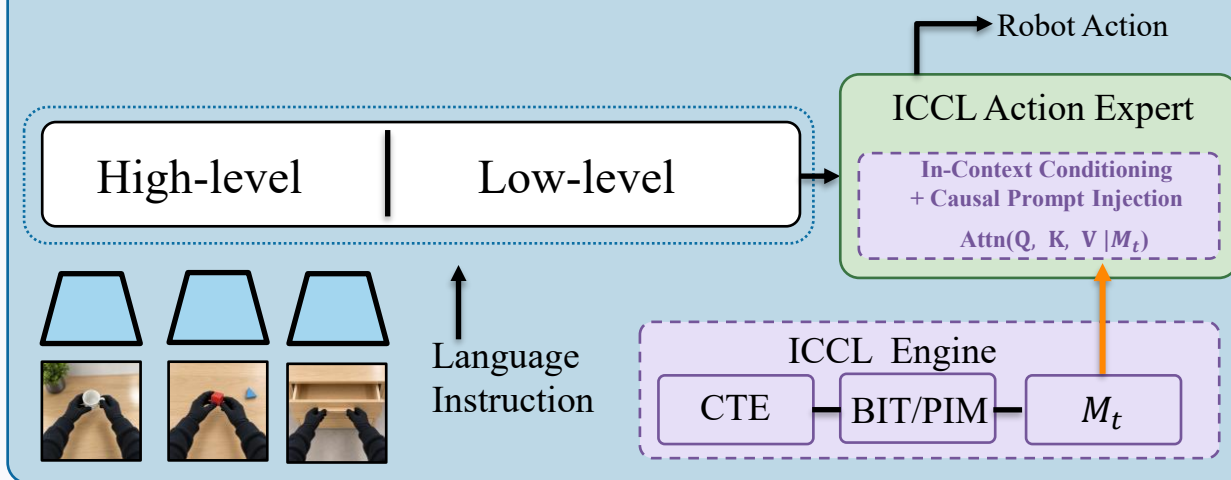


Fold Clothes



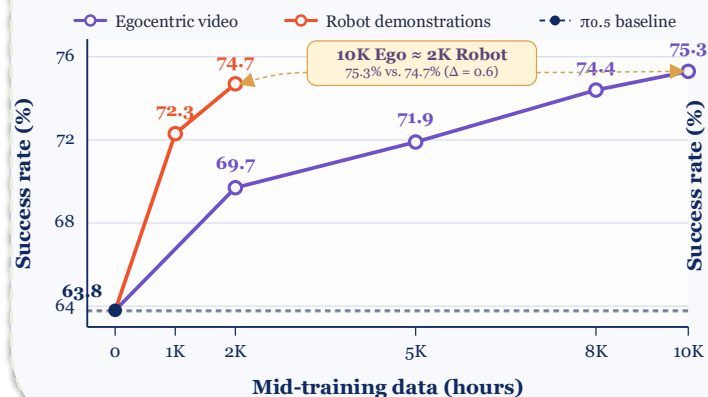
Power Strip Repair

Zeva-Ego: Ego-Enhanced ICCL VLA Policy



Mid-training Data Efficiency

Shared evaluation on RoboTwin manipulation tasks



RealWorld ICCL evolving

Repeated real-world interaction attempts



ICCL Post Training

RoboTwin Post-Training

Turn Switch



Reach Switch

Press Switch

Move Can to Pot



Approach Can

Transfer to Pot

Hang Mug



Grasp Mug

Hang on Rack

ChemLab Post-Training

PlaceBottle



Approach Bottle

Grasp Bottle

PlaceBottle



Transfer Bottle

Place at Target